



# GeoDAS SDV

Geophysical Data Acquisition System



Image courtesy of Anteon Corporation

Situational Awareness

Navigational Accuracy

Obstacle Avoidance

Integrated Systems



Image courtesy of United States Navy

GeoDAS-SDV, tailor-made for Swimmer Delivery Vehicles and other wet subs, is OIC's custom system for real-time navigation, mapping and obstacle avoidance. GeoDAS-SDV is a configurable hardware and software system, typically comprised of a waterproof GPS, sidescan sonar, forward look sonar, compass, doppler velocity log and an onboard computer running our GeoDAS software. The result is a system that offers real-time interface and control for the integrated sensors to provide a superior working environment for vehicle operators, particularly in low-visibility environments.

## Forward Look Sensors

Blueview  
Imagenex  
R2Sonic  
Sonavision  
Tritech  
Ultra

## Sidescan Systems

C-Max  
EdgeTech  
Imagenex  
Klein  
SonarBeam

### DVL NAV Specifications:

Made by RDI  
Workhorse DVL plus compass,  
depth gauge & battery  
Proprietary PDO output, contains  
position, speed, course, heading,  
depth and altitude  
Self-powered (6 hours)

### GPS Specifications:

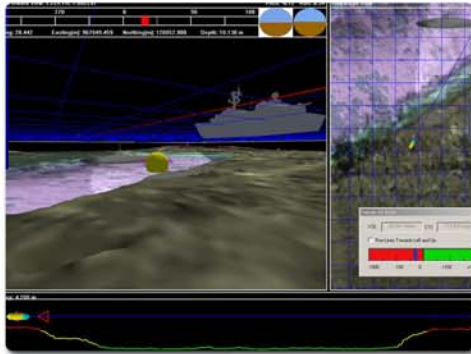
JRC GPS or any NMEA compat-  
ible unit  
50 cm mast  
NMEA out; GGA, VTG, ZDA

### Obstacle Avoidance Specifications:

RS-232 / RS-485 interfaces  
10 – 500 meter range  
Adjustable step size  
Controllable Range, Gain, Sector  
Width & Transmit On/Off  
Integrated Attitude, Navigation and  
Real Time Mosaics

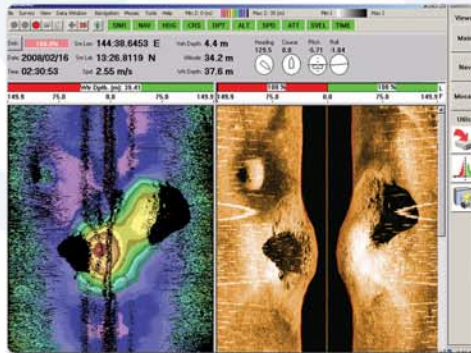
## Fully Submersible

OIC's processing and Acquisition Module (PAM) is the powerhouse of the GeoDAS-SDV system. Features included: sealed enclosure to 10 atmospheres, SUBCONN wet-mateable connectors, ~6 hours mission duration capability independent of host power and push button interface.



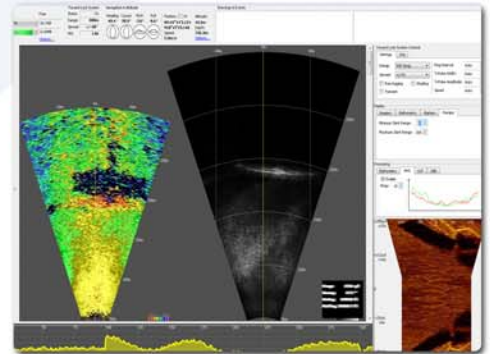
## Real-time Mosaicking

Building on GeoDAS' existing strengths such as real-time mosaicking, multiple sensor inputs and extensive mission planning and analysis capability, GeoDAS-SDV creates a detailed image of the seafloor from sidescan and forward look sensor data.



## 3D Navigation Display

ROver's Eye renders the sub-sea environment using pre-loaded models and data acquired from on-board sensors in real-time.



## Diver Operability

The new GeoDAS interface provides an ideal combination of robust features and ease of use. For the SDV version, all of the features of our standard GeoDAS software have been modified to be easily operated in a push-button environment, free from keyboard and menu requirements.



## Oceanic Imaging Consultants, Inc.

Founded in 1993, OIC provides seafloor mapping software, systems and services to the world's military, government, commercial, and academic markets. With a solid understanding of the requirements of the hydrographic community and an emphasis on providing quality customer support, OIC should be your first stop for all of your seafloor mapping needs.



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